

«EMR-based simulation using Simcenter Amesim»

Dr. Calin HUSAR,
Siemens Industry Software Romania

SIEMENS

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Simcenter Amesim software

2

EMR library into Simcenter Amesim

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Structural vs. Functional representation

4

PANDA EMR simulations



EMR'25, Lille (France)

« Simcenter Amesim »

EMR-based simulation using Simcenter Amesim

- Simcenter Amesim -

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EMR'25, Lille, July 2025



Model-based
system testing

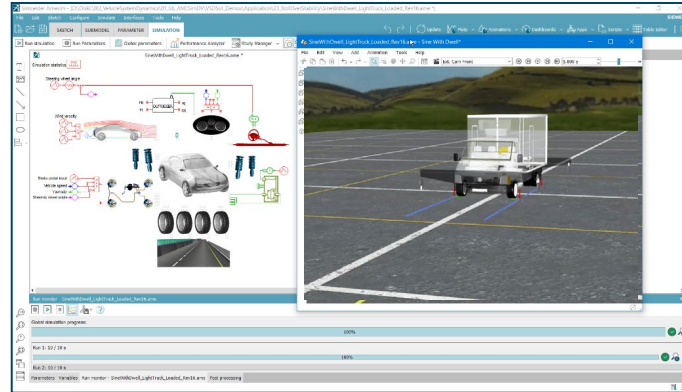
Industry
specific

Vehicle integration
Vehicle electrification
ADAS and
autonomous vehicle
Powertrain controls
Engine design
Aftertreatment
Transmission
HVAC
Engine thermal
management
Vehicle dynamics
Powertrain
subsystems

Pre-design
Systems sizing
and integration

Performance
balancing

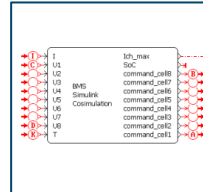
Controls
validation



Scalable
simulation

Connecting
“mechanical” –
“controls”

Model reduction
for real-time

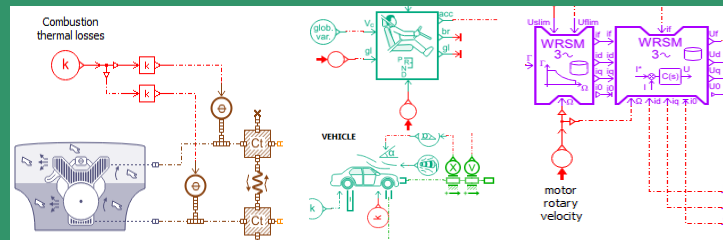


Co-simulation

Open and
customizable

>48 libraries

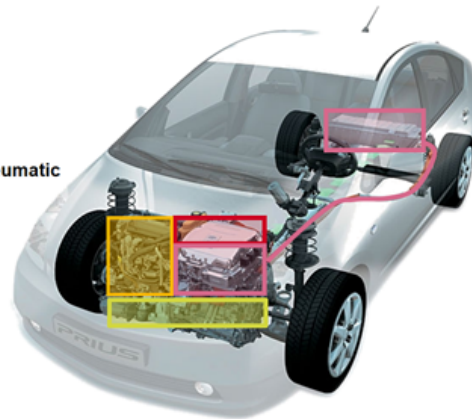
>6,500 multi-
physics models



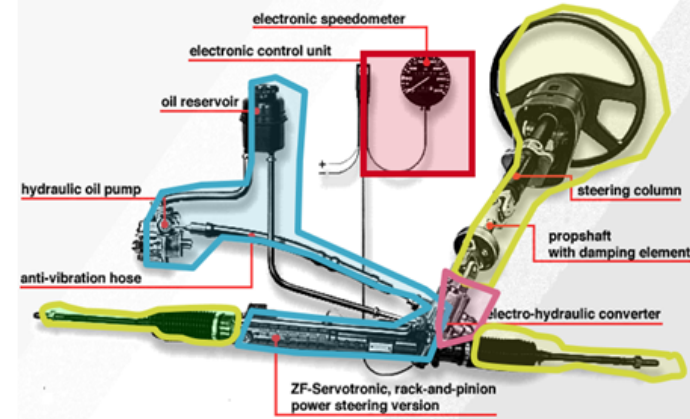
Hydraulics
Pneumatics
Thermal
Electrical
Mechanical
Signals

System
architecture
management

- Control
- Electric
- Hydraulic / Pneumatic
- Mechanic
- Thermal

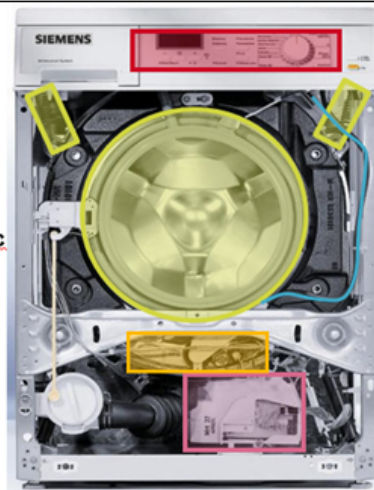


a: Hybrid vehicle

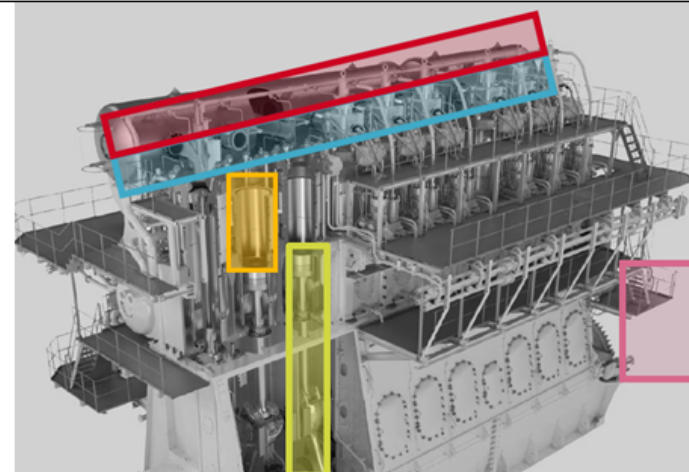


b: Electro-hydraulic power steering

- Control
- Electric
- Hydraulic / Pneumatic
- Mechanic
- Thermal



c: Washing machine



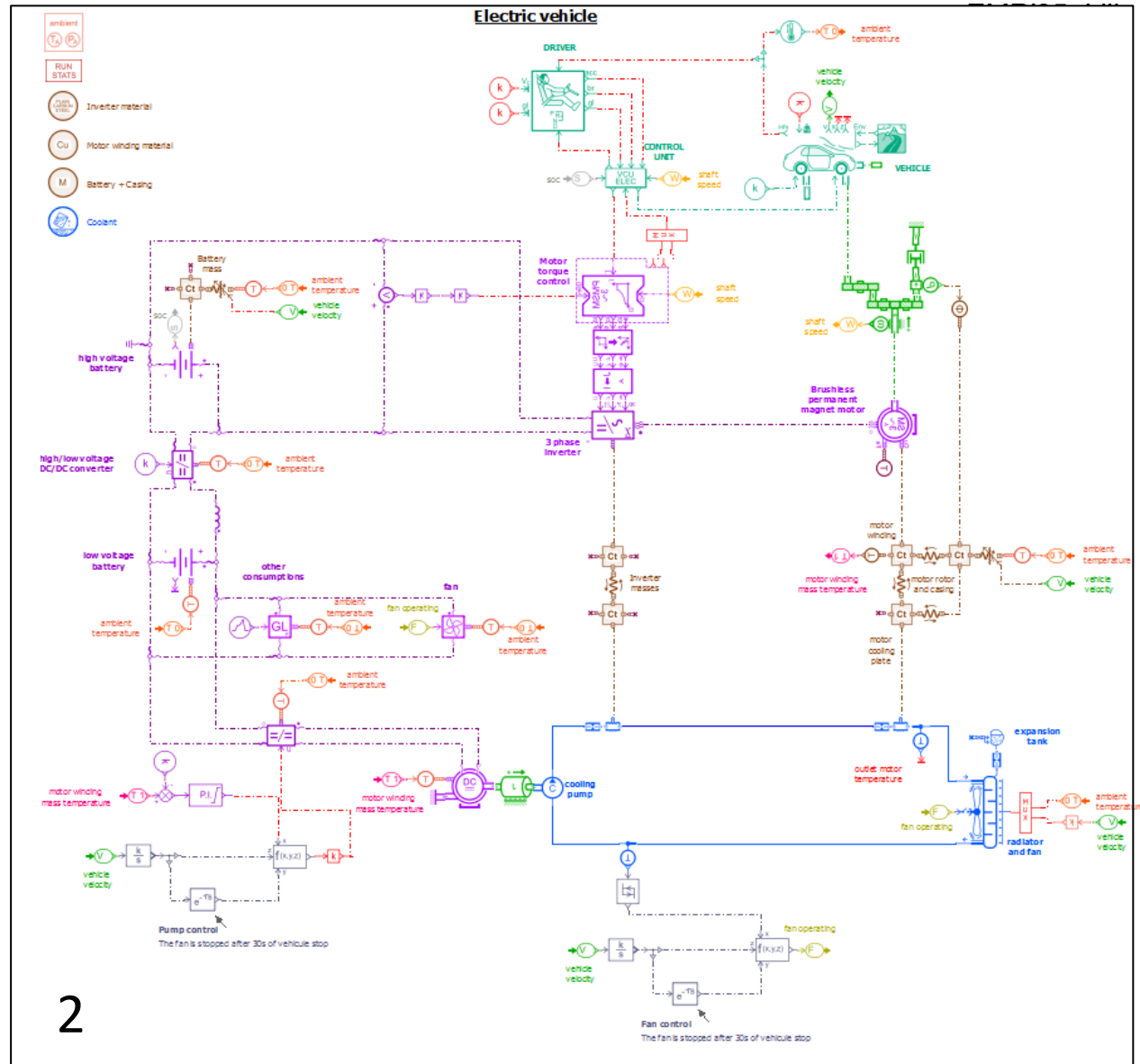
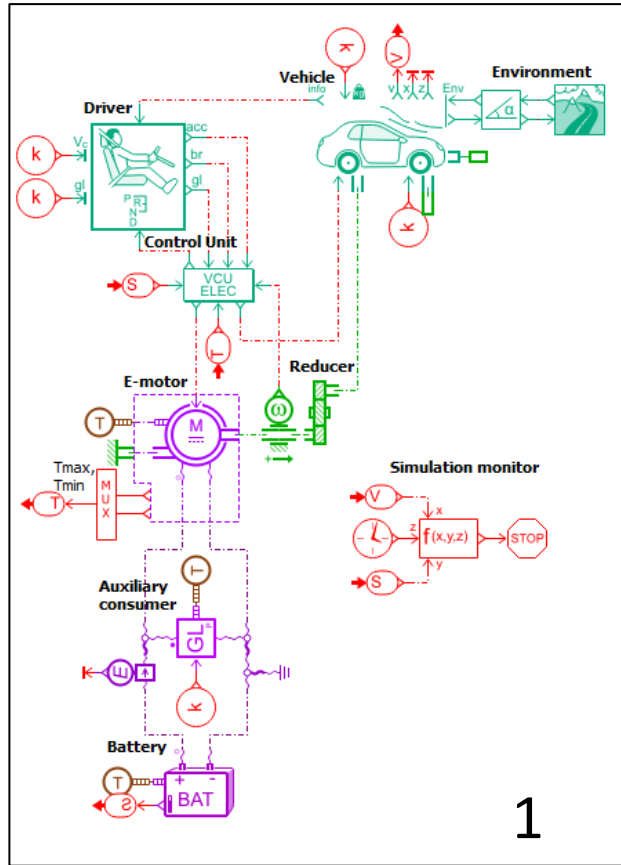
d: IC Engine

EMR-based simulation using Simcenter Amesim

Example of Simecenter Amesim

6

July 2025





EMR'25, Lille (France)

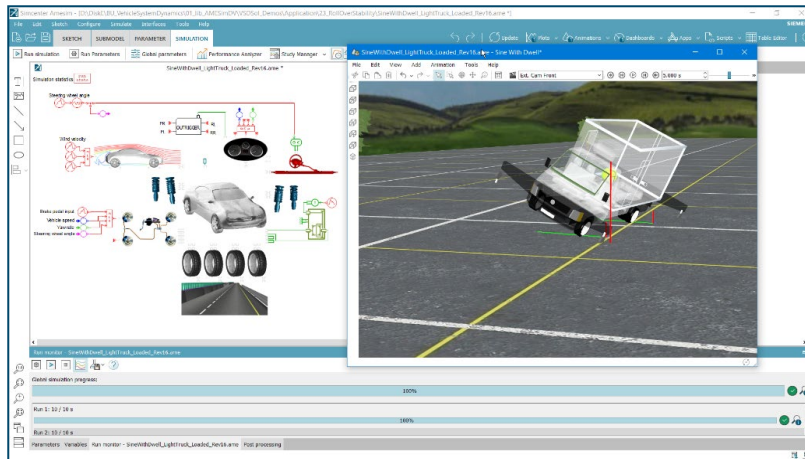
«EMR library into Simcenter Amesim»

EMR-based simulation using Simcenter Amesim

- Simcenter Amesim - New EMR library-

EMR'25, Lille, July 2025

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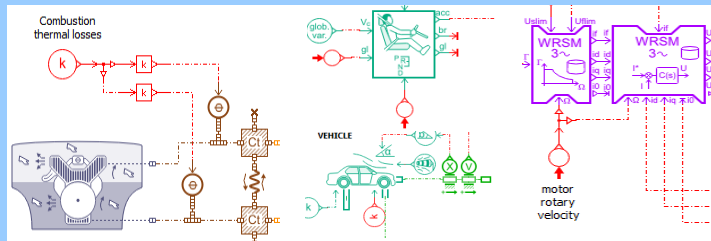
Model-based
system testing

Pre-design

Systems sizing &
integration

Performance
balancing

Controls validation



48 libraries
(6500 models)

- Hydraulics
- Pneumatics
- Thermal
- Electrical
- Mechanical
- Signals, etc.

Advanced industrial
Multiphysics simulation
package

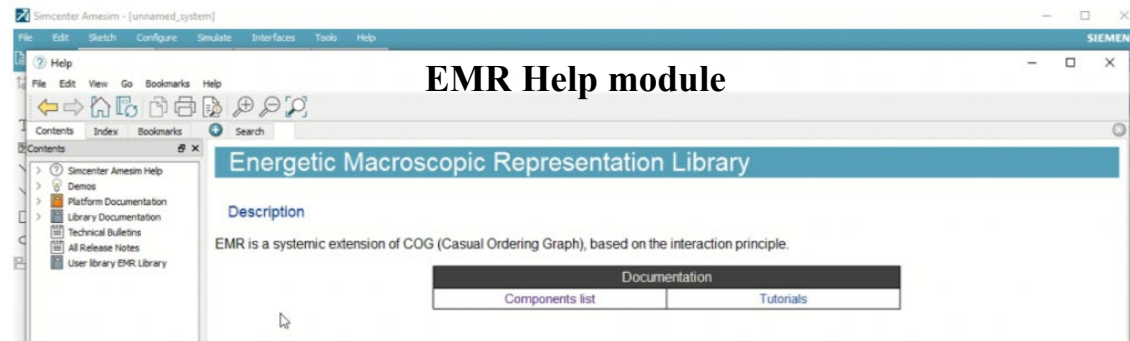
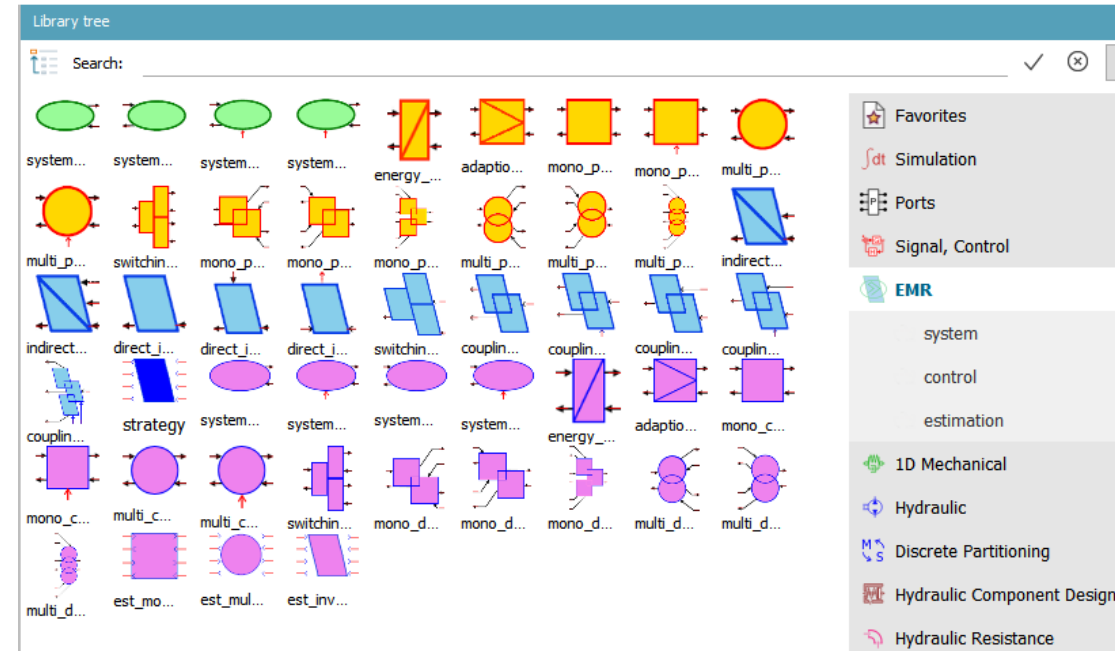
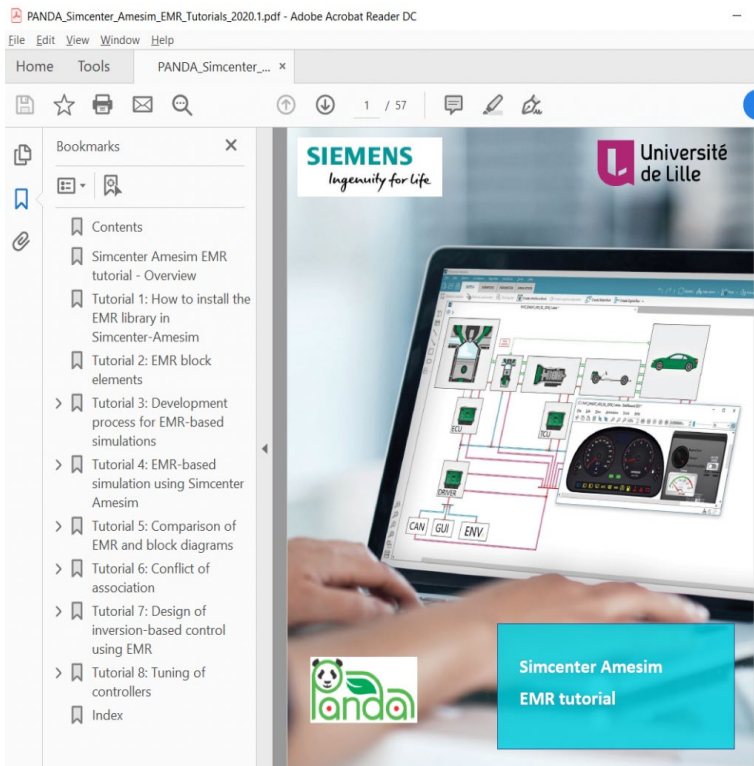
based on
**structural libraries
for models**
and
a functional library
for control



new **EMR-based
functional library**
for models
& control

New and dedicated **EMR library** where all components defined by EMR theory are included

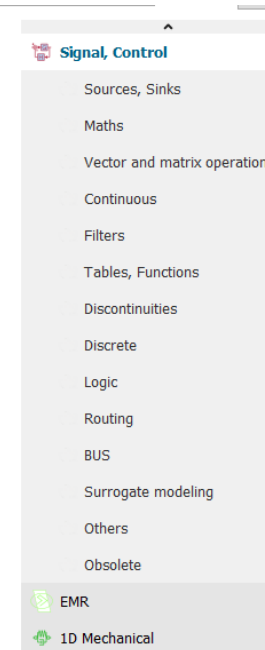
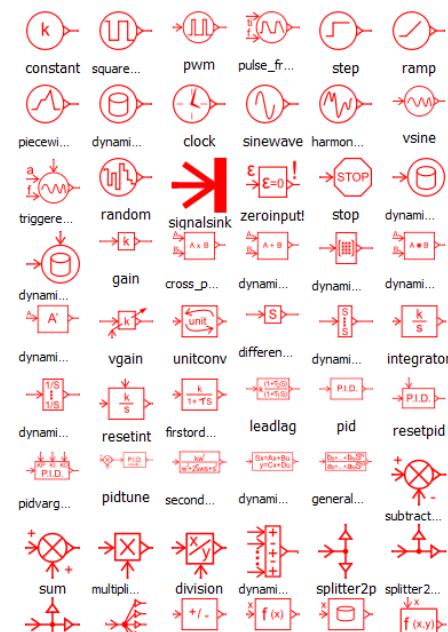
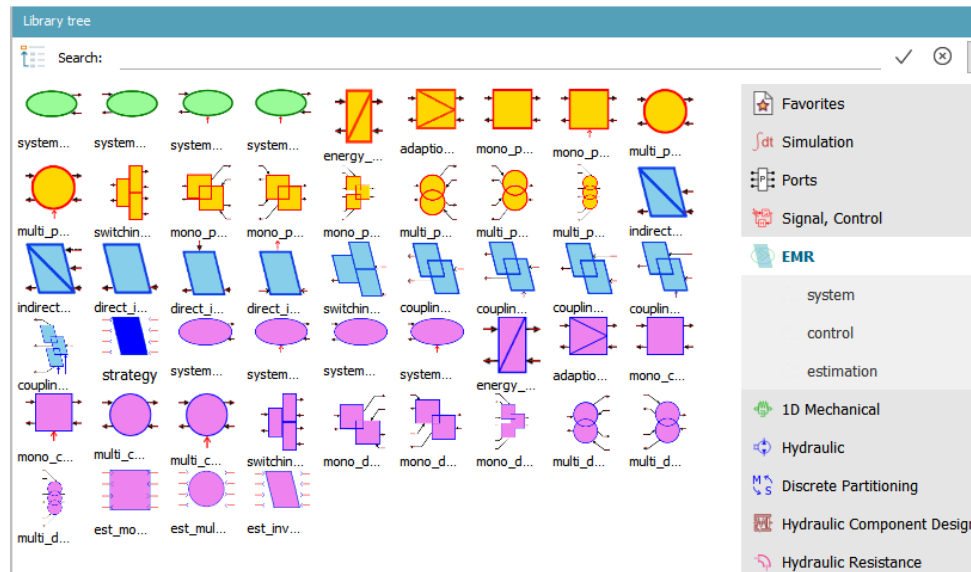
Help module with the description of each EMR element and new developed EMR tutorials included



New EMR library



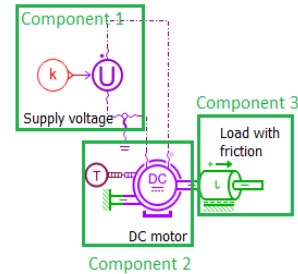
Signal & Control library



EMR simulations in Simcenter Amesim

Step 1.

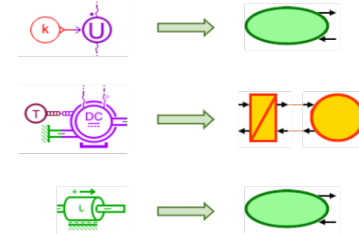
Definition of the different subsystems to be considered



System level choice

Step 2.

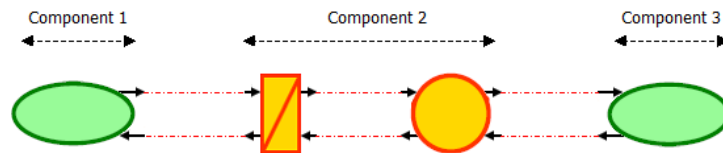
Definition of the equivalent EMR elements



Component models vs. EMR elements

Step 3.

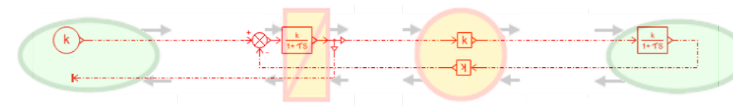
Interconnection of the EMR elements while resolving the conflict of association



EMR diagram

Step 4.

Integration of the model equation in the EMR element using the Signal and Control library

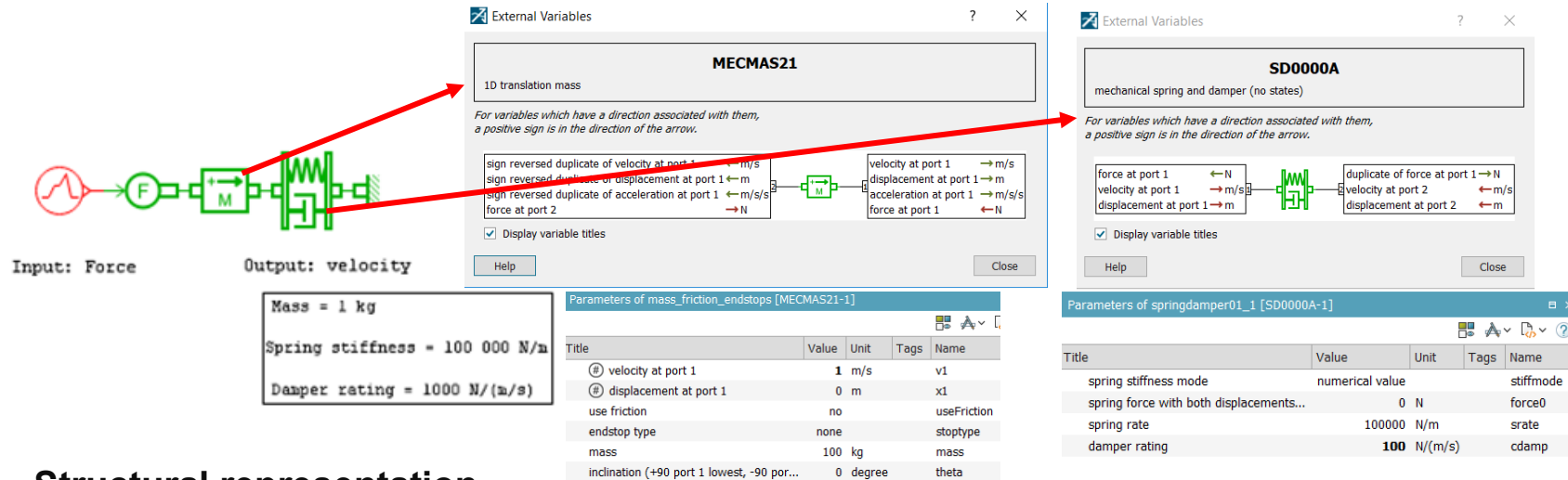


Equation model



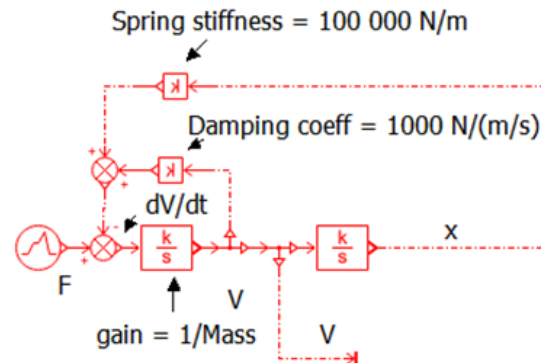
EMR'25, Lille (France)

«Structural vs. Functional representation »

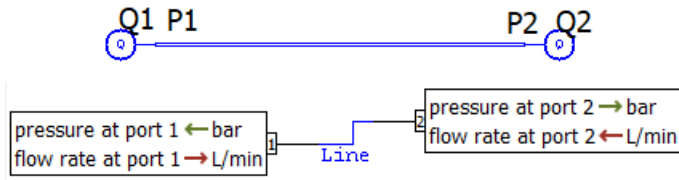


Structural representation

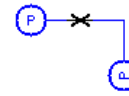
Functional representation



Structural representation



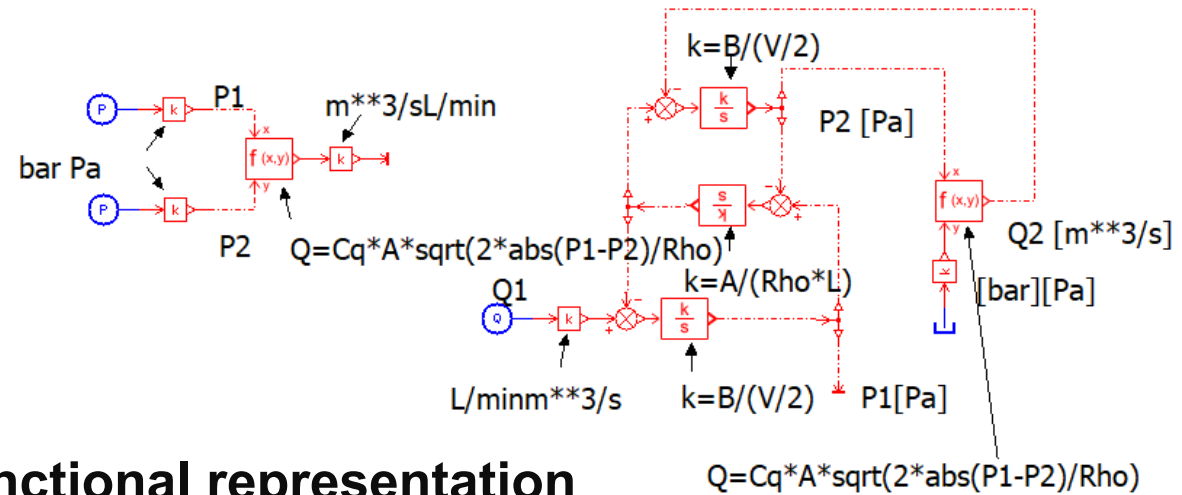
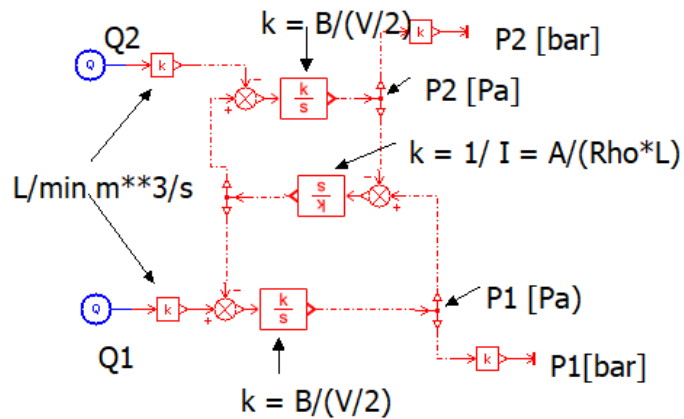
Model Line: C,I,C (Volume, Inertia, Volume)



Restriction



Circuit



Functional representation

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« PANDA EMR simulation »

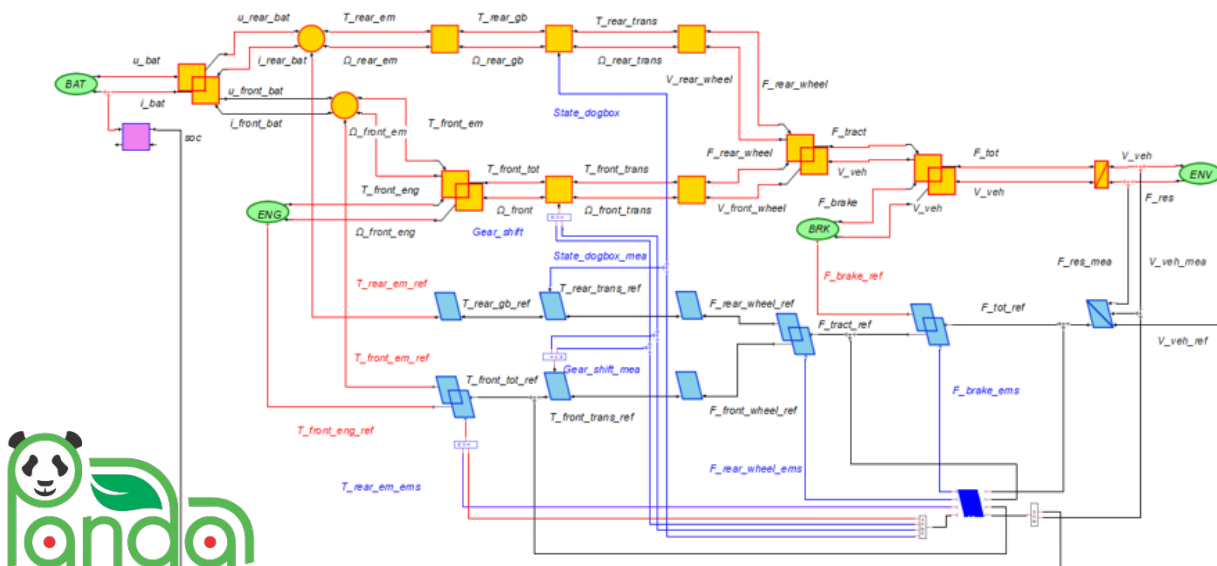


PANDA Simcenter Amesim EMR n-level vehicle models based on:

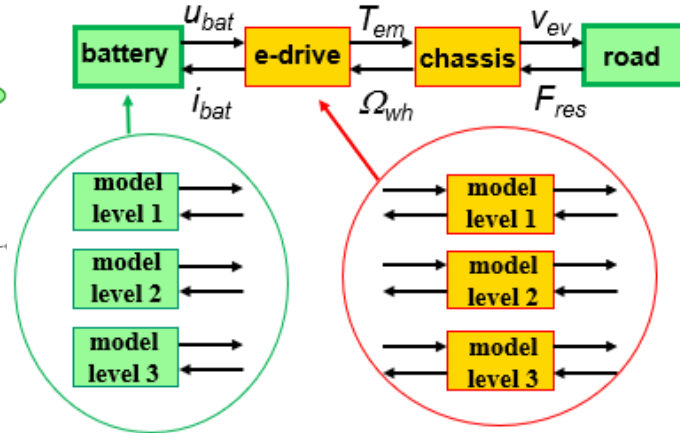
Renault Zoe (BEV)

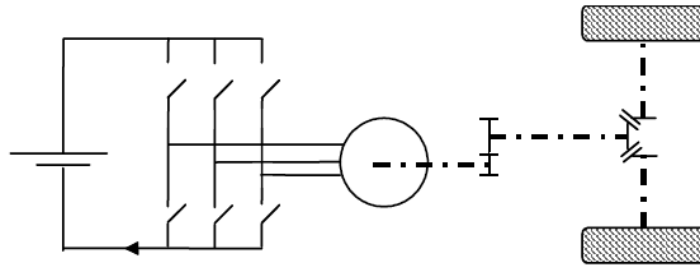
Mobypost (FCV)

Valeo Demo Car (P-HEV)

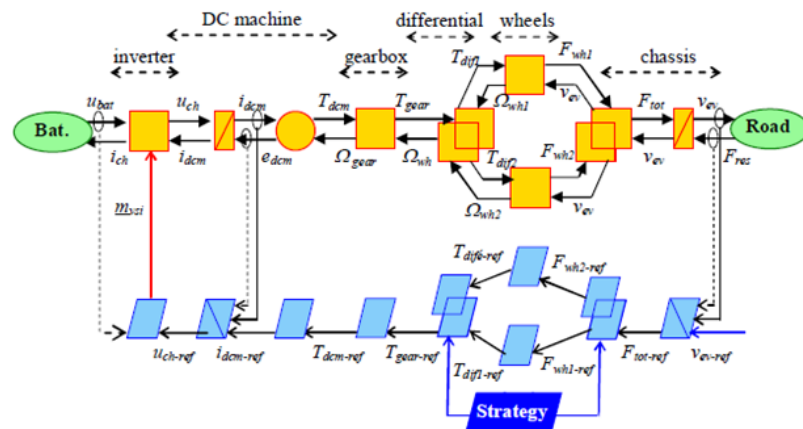


Powerful Advanced N-Level Digital Architecture
for models of electrified vehicles and their components





- Battery - modelled by a simple source of D.C. voltage;
- PMSM - replaced by a DC machine;
- The Chopper - considered with a constant efficiency;
- Mechanical transmission - composed of a gearbox, a mechanical differential and one equivalent wheel;
- The chassis - represented with an equivalent mass.



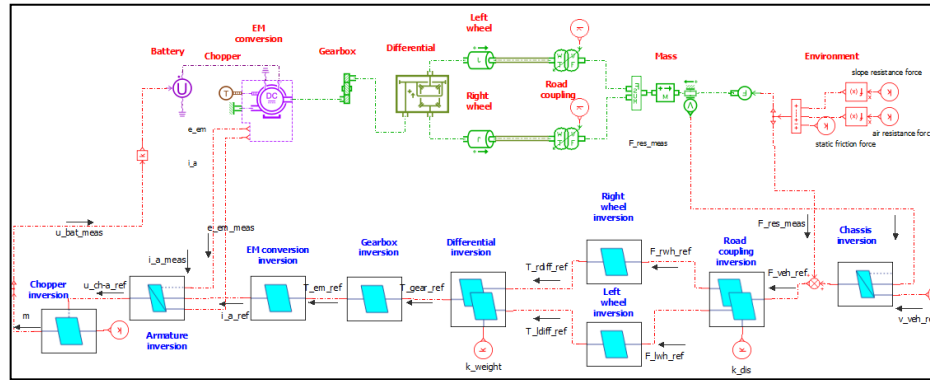
Global Parameter Setup - EV_19.ame

Right click to set global parameters: Search: ☐ ☐ More >

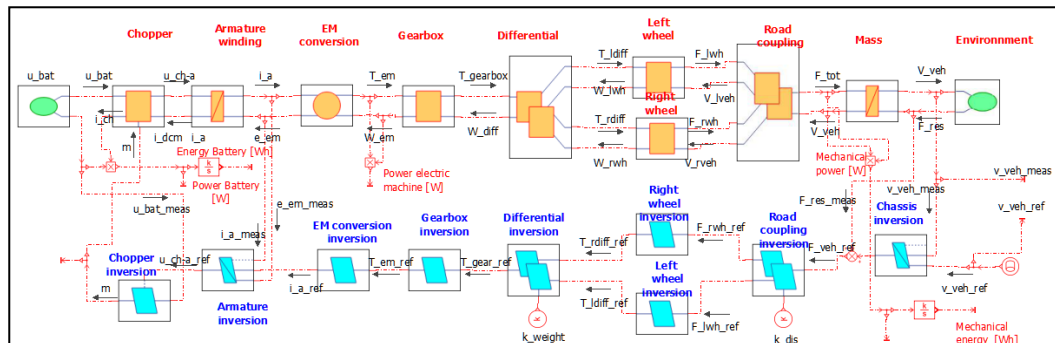
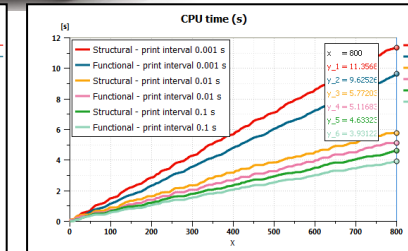
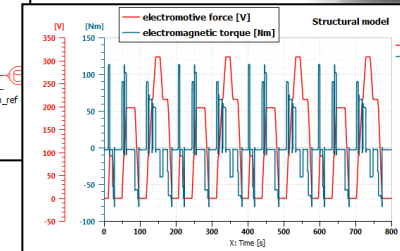
Name	Title	Value	Unit
BATpV_batt	battery tension	400	V
EMpU_arm_nom	DC nominal tensi...	400	V
EMpI_arm_nom	DC nominal curr...	162	A
EMpN_nom	nominal speed	2840	rpm
EMpN_max	max speed	6000	rpm
EMpW_nom	nominal angular ...	$3.14/30 * EMpN_{...}$	rad/sec
EMpP_nom	DC nominal power	65000	W
EMpDamp	viscous friction	0.1	Nm*sec/rad
EMpJ	equivalent inerti...	4.8	kg*m^2
EMpR_arm	DC resistance	0.35	Ohm
EMpL_arm	DC inductance	0.0065	H
EMpK_em	emf constant	$(EMpU_{arm_no...}$	V*sec/rad
EMpK_tq	torque constant	EMpK_em	Nm/A
EMpK_arm	Gain of the arma...	$1/EMpR_{arm}$	null
EMpT_arm	Time constant of...	$EMpL_{arm}/EMpR_{...}$	null
CHp_eff	Chopper efficiency	0.95	null
MTpGear_eff	Gearbox efficiency	0.8	null
MTpk_gear	Gearbox ratio	5	null
MTpD_wheel	wheel diameter	0.52	m
MTpR_wheel	wheel radius	$MTpD_{wheel}/2$	m
MTpJ_wheel	wheel inertia	4.3	kg.m^2
CHApM_eq	Equivalent mass	1600	kg
CHApK_eq	Velocity gain	$1/CHApM_{eq}$	null
RDpwheelbase	wheelbase	2.4	m
RDpw_ev	EV width	1.6	m
RDpg	gravity	9.81	m/s^2
RDpA	frontal area	2	m^2
RDpCx	Drag coefficient	0.35	null
RDpro	Density of the air	1.223	kg/m^3

Help OK Cancel Apply

Classical Simcenter Amesim structural library



Simulation of Renault ZOE



- same model / control
- same accuracy
- -15% of computation time with the functional library

New EMR-based (functional) library in Simcenter Amesim



EMR'25, Lille (France)

« BIOGRAPHIES AND REFERENCES »



Dr. Calin HUSAR , RTD engineer
Siemens Industry Software Romania

PhD in Mechanical Engineering at “Transilvania” University Brasov (2009)
Research topics: autonomous driving, electric and hybrid vehicles

calin.husar@siemens.com

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Thanks for your attention !

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